Prof. Michael Beetz  
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[J1] Jan Bandouch, Odest Chadwicke Jenkins and Michael Beetz,
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[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner, Moritz Tenorth, Lars Kunze, Nico Blodow and Dejan Pangercic,
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[J4] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz,
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Segmentation of Cluttered Scenes through Interactive Perception,

[C3] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz,
Elaborative Evaluation of RGB-D based Point Cloud Registration for Personal Robots,

[C4] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz,
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[C5] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers,
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[C6] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
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[C8] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz, 
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[C9] Ingo Kresse and Michael Beetz, 
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[C11] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 

[C12] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C13] Ferenc Balint-Benczedi, Zoltan-Csaba Marton and Michael Beetz, 
Efficient Part-Graph Hashes for Object Categorization, 
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[C20] Daniel Nyga and Michael Beetz, 
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[C21] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
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[C23] Lucian Cosmin Goron, Zoltan Csaba Marton, Gheorghe Lazea and Michael Beetz, 
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Perzylo, Björn Schießle, Oliver Zweigle and René van de Molengraft, 
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and Categorize Unknown Furniture Pieces in 3D Laser Scans, 

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[C9] Nico Blodow, Lucian Cosmin Goron, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
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[C11] Alexis Maldonado, Ulrich Klank and Michael Beetz, 
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Putting People’s Common Sense into Knowledge Bases of Household Robots, 

[C13] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz, 
Hierarchical Object Geometric Categorization and Appearance Classification for Mobile Manipulation, 

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[C18] Radu Bogdan Rusu, Nico Blodow and Michael Beetz,
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[C19] Zoltan Csaba Marton, Radu Bogdan Rusu and Michael Beetz,
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[C20] Morten Rufus Blas, Radu Bogdan Rusu, Mogens Blanke and Michael Beetz,
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[C18] Moritz Tenorth and Michael Beetz,
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[C19] Dominik Jain, Lorenz Mösenlechner and Michael Beetz,
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[C20] Lorenz Mösenlechner, Armin Müller and Michael Beetz,
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[C21] Zahid Riaz, Michael Beetz and Bernd Radig,
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[J1] Martin Buss, Michael Beetz and Dirk Wollherr,
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[C1] Nicolai v. Hoyningen-Huene, Bernhard Kirchlechner and Michael Beetz,
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[C2] Freek Stulp, Wolfram Koska, Alexis Maldonado and Michael Beetz,
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[C15] Dominik Jain, Bernhard Kirchlechner and Michael Beetz,
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[C6] Freek Stulp and Michael Beetz,
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[C7] Armin Müller and Michael Beetz,
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[C8] Markus Geipel and Michael Beetz,
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[C9] Matthias Wimmer, Bernd Radig and Michael Beetz,
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  Reliable Multi Robot Coordination Using Minimal Communication and Neural Prediction,

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