[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz, 
*Simulation-based Temporal Projection of Everyday Robot Object Manipulation*,
Yolum, Tumer, Stone and Sonenberg(Eds.), *Proc. of the 10th Int. Conf. on Autonomous Agents and Multiagent Systems (AAMAS 2011)*, Taipei, Taiwan, IFAAMAS, May, 2–6 2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz, 
*Logic Programming with Simulation-based Temporal Projection for Everyday Robot Object Manipulation*,

[J1] Radu Bogdan Rusu, Zoltan Csaba Marton, Nico Blodow, Mihai Dolha and Michael Beetz, 
*Towards 3D Point Cloud Based Object Maps for Household Environments*,

[C1] Zoltan Csaba Marton, Nico Blodow, Mihai Dolha, Moritz Tenorth, Radu Bogdan Rusu and Michael Beetz, 
*Autonomous Mapping of Kitchen Environments and Applications*,

[C2] Michael Beetz, Freek Stulp, Bernd Radig, Jan Bandouch, Nico Blodow, Mihai Dolha, Andreas Fedrizzi, Dominik Jain, Uli Klank, Ingo Kresse, Alexis Maldonado, Zoltan Marton, Lorenz Mösenlechner, Federico Ruiz, Radu Bogdan Rusu and Moritz Tenorth, 
*The Assistive Kitchen – A Demonstration Scenario for Cognitive Technical Systems*,
*IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN)*, Muenchen, Germany, 1-8, 2008.

[C3] Radu Bogdan Rusu, Zoltan Csaba Marton, Nico Blodow, Mihai Emanuel Dolha and Michael Beetz, 
*Functional Object Mapping of Kitchen Environments*,