Ulrich Klank  

List of Publications

[C1] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz,  
Robots that Validate Learned Perceptual Models,  
*IEEE International Conference on Robotics and Automation (ICRA)*, St. Paul, MN, USA,  
May 14–18 2012.

[PhD1] Ulrich Klank,  
Everyday Perception for Mobile Manipulation in Human Environments,  
Technische Universität München, 2012.

[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz,  
Web-enabled Robots – Robots that Use the Web as an Information Resource,  

[C1] Ulrich Klank, Daniel Carton and Michael Beetz,  
Transparent Object Detection and Reconstruction on a Mobile Platform,  
*IEEE International Conference on Robotics and Automation (ICRA)*, Shanghai, China,  
May, 9–13 2011.

[C2] Michael Beetz, Ulrich Klank, Alexis Maldonado, Dejan Pangercic and Thomas Rühr,  
Robotic Roommates Making Pancakes - Look Into Perception-Manipulation Loop,  

[C3] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth,  
Robotic Roommates Making Pancakes,  
11th *IEEE-RAS International Conference on Humanoid Robots*, Bled, Slovenia, October,  
26–28 2011.

[C4] Ingo Kresse, Ulrich Klank and Michael Beetz,  
Multimodal Autonomous Tool Analyses and Appropriate Application,  
11th *IEEE-RAS International Conference on Humanoid Robots*, Bled, Slovenia, October,  
26–28 2011.

[J1] Michael Beetz, Freek Stulp, Piotr Esden-Tempski, Andreas Fedrizzi, Ulrich Klank, Ingo Kresse, Alexis Maldonado and Federico Ruiz,  
Generality and Legibility in Mobile Manipulation,  

[C1] Alexis Maldonado, Ulrich Klank and Michael Beetz,  
Robotic grasping of unmodeled objects using time-of-flight range data and finger torque information,  
[C1] Ulrich Klank, Dejan Pangercic, Radu Bogdan Rusu and Michael Beetz,
Real-time CAD Model Matching for Mobile Manipulation and Grasping,

[C2] Zoltan Csaba Marton, Radu Bogdan Rusu, Dominik Jain, Ulrich Klank and Michael Beetz,
Probabilistic Categorization of Kitchen Objects in Table Settings with a Composite Sensor,

[C3] Ulrich Klank, Muhammad Zeeshan Zia and Michael Beetz,
3D Model Selection from an Internet Database for Robotic Vision,

[C4] Muhammad Zeeshan Zia, Ulrich Klank and Michael Beetz,
Acquisition of a Dense 3D Model Database for Robotic Vision,
International Conference on Advanced Robotics (ICAR), 2009.

[C5] Li Sun, Ulrich Klank and Michael Beetz,
EYEWATCHME - 3D Hand and object tracking for inside out activity analysis,

[C6] Michael Beetz, Freek Stulp, Bernd Radig, Jan Bandouch, Nico Blodow, Mihai Dolha, Andreas Fedrizzi, Dominik Jain, Uli Klank, Ingo Kresse, Alexis Maldonado, Zoltan Marton, Lorenz Mösenlechner, Federico Ruiz, Radu Bogdan Rusu and Moritz Tenorth,
The Assistive Kitchen – A Demonstration Scenario for Cognitive Technical Systems,

[J1] Ulrich Klank, N. Padoy, H. Feussner and N. Navab,
Automatic feature generation in endoscopic images,

[C1] Michael Beetz, Freek Stulp, Bernd Radig, Jan Bandouch, Nico Blodow, Mihai Dolha, Andreas Fedrizzi, Dominik Jain, Uli Klank, Ingo Kresse, Alexis Maldonado, Zoltan Marton, Lorenz Mösenlechner, Federico Ruiz, Radu Bogdan Rusu and Moritz Tenorth,
The Assistive Kitchen – A Demonstration Scenario for Cognitive Technical Systems,
IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN), Muenchen, Germany, 1-8, 2008.