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[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz,
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[C2] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz,
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[C3] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers,
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[C4] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
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[C5] Ferenc Balint-Benczedi, Zoltan-Csaba Marton and Michael Beetz,
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[C6] Zoltan-Csaba Marton, Ferenc Balint-Benczedi, Florian Seidel, Lucian Cosmin Goron and Michael Beetz,
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[C8] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
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S. Stramigioli, H.Bruyninckx, P. Doherty, A. Kleiner, V. Lippiello, A. Finzi, B. Siciliano, 
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[C4] Nico Blodow, Dominik Jain, Zoltan-Csaba Marton and Michael Beetz,
*Perception and Probabilistic Anchoring for Dynamic World State Logging*,

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*IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN), Muenchen, Germany, 1-8, 2008.*

[C7] Radu Bogdan Rusu, Jan Bandouch, Zoltan Csaba Marton, Nico Blodow and Michael Beetz,
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