[J1] Freek Stulp, Hans Utz, Michael Isik and Gerd Mayer,
*Implicit Coordination with Shared Belief: A Heterogeneous Robot Soccer Team Case Study,*

[C1] S. Sosnowski, C. Mayer, K. Kühnlenz and B. Radig,
*Mirror my emotions! Combining facial expression analysis and synthesis on a robot,*

[C2] Frank Wallhoff, Tobias Rehrl, Christoph Mayer and Bernd Radig,
*Real-Time Face and Gesture Analysis for Human-Robot Interaction,*

[C3] C. Mayer, S. Sosnowski, K. Kühnlenz and B. Radig,
*Towards robotic facial mimicry: system development and evaluation,*

*A Distributed Many-Camera System for Multi-Person Tracking,*
R. Wichert and B. de Ruyter(Eds.), *Proceedings of the First International Joint Conference on Ambient Intelligence (AmI 2010)*, Springer Lecture Notes in Computer Science, November 2010.

*Multi Joint Action in CoTeSys — Setup and Challenges,*
CoTeSys-TR-10-01, CoTeSys Cluster of Excellence: Technische Universität München &38; Ludwig-Maximilians-Universität München, Munich, Germany, June 2010.