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[C5] Moritz Tenorth and Michael Beetz,  
**Knowledge Processing for Autonomous Robot Control**,  

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,  
**Semantic Object Maps for Household Tasks**,  

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr,  
**CRAM – a Cognitive Robot Abstract Machine**,  

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi,  
**RoboEarth Action Recipe Execution**,  

[C9] Moritz Tenorth and Michael Beetz,  
**Exchange of Action-related Information among Autonomous Robots**,  

[C10] Moritz Tenorth and Michael Beetz,  
**A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects**,  

[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,  
**Semantic Object Maps for Robotic Housework - Representation, Acquisition and Use**,  

**The SHERPA project: smart collaboration between humans and ground-aerial robots for improving rescuing activities in alpine environments**,  
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[C4] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,
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[C5] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
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