KnowRob: Knowledge processing for robots List of Publications

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
**Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework**, 

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermsdörfer, 
**Action sequencing and error production in stroke patients with apraxia – Behavioral modeling using Bayesian Logic Networks**, 

[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
**Learning Probability Distributions over Partially-Ordered Human Everyday Activities**, 

[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz, 
**Ensembles of Strong Learners for Multi-cue Classification**, 
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[C2] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
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[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
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[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba, 
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[C5] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
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[C6] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth,
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[C7] Manabu Saito, Haseru Chen, Kei Okada, Masayuki Inaba, Lars Kunze and Michael Beetz,
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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch, 
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[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth, 
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[C1] Moritz Tenorth, Daniel Nyga and Michael Beetz, 
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[C2] Moritz Tenorth and Michael Beetz, 
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[C3] Dejan Pangercic, Moritz Tenorth, Dominik Jain and Michael Beetz, 
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[C4] Michael Beetz, Lorenz Mösenlechner and Moritz Tenorth, 
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[C5] Lars Kunze, Moritz Tenorth and Michael Beetz, 
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