KnowRob: Knowledge processing for robots List of Publications

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework, 

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermßöer, 
Action sequencing and error production in stroke patients with apraxia – Behavioral modeling using Bayesian Logic Networks, 

[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
Learning Probability Distributions over Partially-Ordered Human Everyday Activities, 

[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz, 
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[C1] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz, 
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[C2] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments, 

[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments, 

[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba, 
Searching Objects in Large-scale Indoor Environments: A Decision-theoretic Approach, 
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[J2] Markus Waibel, Michael Beetz, Raffaello D’Andrea, Rob Janssen, Moritz Tenorth, Javier Civera, Jos Elfring, Dorian Gálvez-López, Kai Häussermann, J.M.M. Montiel, Alexander Perzylo, Björn Schießle, Oliver Zweigle and René van de Molengraft,
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[C3] Daniel Nyga, Moritz Tenorth and Michael Beetz,
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[C4] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,
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[C5] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
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[C6] Michael Beetz, Ulrich Klang, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth,
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[C7] Manabu Saito, Haseru Chen, Kei Okada, Masayuki Inaba, Lars Kunze and Michael Beetz,
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