[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz, 
*Simulation-based Temporal Projection of Everyday Robot Object Manipulation,* 
Yolum, Tumer, Stone and Sonenberg(Eds.), *Proc. of the 10th Int. Conf. on Autonomous Agents and Multiagent Systems (AAMAS 2011),* Taipei, Taiwan, IFAAMAS, May, 2–6 2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz, 
*Logic Programming with Simulation-based Temporal Projection for Everyday Robot Object Manipulation,* 

[C1] Lorenz Mösenlechner and Michael Beetz, 
*Using Physics- and Sensor-based Simulation for High-fidelity Temporal Projection of Realistic Robot Behavior,* 
19th International Conference on Automated Planning and Scheduling (ICAPS’09), 2009.