ProbCog: Probabilistic Cognition for Technical Systems

[List of Publications]

[C1] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
Learning Probability Distributions over Partially-Ordered Human Everyday Activities, 

[C1] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz, 
Learning Organizational Principles in Human Environments, 

[PhD1] Dominik Jain, 

[C1] Dominik Jain, Klaus von Gleissenthall and Michael Beetz, 
Bayesian Logic Networks and the Search for Samples with Backward Simulation and Abstract Constraint Learning, 

[C2] Paul Maier, Dominik Jain and Martin Sachenbacher, 
Compiling AI Engineering Models for Probabilistic Inference, 

[C3] Dominik Jain, 
Knowledge Engineering with Markov Logic Networks: A Review, 
DKB 2011: Proceedings of the Third Workshop on Dynamics of Knowledge and Belief, 2011.

[C4] William R. Murray and Dominik Jain, 
Modeling Cognitive Frames for Situations with Markov Logic Networks, 

[C5] Maier, Paul, Jain, Dominik, Sachenbacher and Martin, 
Diagnostic Hypothesis Enumeration vs. Probabilistic Inference for Hierarchical Automata Models, 
ProbCog: Probabilistic Cognition for Technical Systems

List of Publications

[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch, 
Towards Automated Models of Activities of Daily Life, 

[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth, 
Towards Performing Everyday Manipulation Activities, 

[J3] Moritz Tenorth, Dominik Jain and Michael Beetz, 
Knowledge Representation for Cognitive Robots, 

[C1] Dominik Jain, Andreas Barthels and Michael Beetz, 
Adaptive Markov Logic Networks: Learning Statistical Relational Models with Dynamic Parameters, 

[C2] Dominik Jain and Michael Beetz, 
Soft Evidential Update via Markov Chain Monte Carlo Inference, 

[C3] Paul Maier, Dominik Jain, Stefan Waldherr and Martin Sachenbacher, 
Plan Assessment for Autonomous Manufacturing as Bayesian Inference, 

[C4] Dejan Pangercic, Moritz Tenorth, Dominik Jain and Michael Beetz, 
Combining Perception and Knowledge Processing for Everyday Manipulation, 

[C5] Nico Blodow, Dominik Jain, Zoltan-Csaba Marton and Michael Beetz, 
Perception and Probabilistic Anchoring for Dynamic World State Logging, 

[C6] Moritz Tenorth, Lars Kunze, Dominik Jain and Michael Beetz, 
KNOWROB-MAP – Knowledge-Linked Semantic Object Maps, 

[R1] Moritz Tenorth and Michael Beetz, 
Deliverable D5.2: The RoboEarth Language – Language Specification, 


