Prof. Michael Beetz  
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RoboSherlock: Unstructured Information Processing Framework for Robotic Perception,  
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Part-Based Geometric Categorization and Object Reconstruction in Cluttered Table-Top Scenes,  

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz,  
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[J2] Moritz Tenorth and Michael Beetz,  
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[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz,  
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[C3] Lorenz Mösenlechner and Michael Beetz,  
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[C2] Karol Hausman, Christian Bersch, Dejan Pangercic, Sarah Osentoski, Zoltan-Csaba Marton and Michael Beetz,
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[C3] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz,
Elaborative Evaluation of RGB-D based Point Cloud Registration for Personal Robots,

[C4] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz,
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[C5] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers,
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,
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[C8] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz, 
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[C12] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

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[C21] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
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Wykowska, Agnieszka, Maldonado, Alexis, Beetz, Michael, Schuboe and Anna,

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[C13] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz,
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Multi Joint Action in CoTeSys — Setup and Challenges,  

[R2] Moritz Tenorth and Michael Beetz,  
Deliverable D5.2: The RoboEarth Language – Language Specification,  

[J1] Radu Bogdan Rusu, Aravind Sundaresan, Benoit Morisset, Kris Hauser, Motilal Agrawal, Jean-Claude Latombe and Michael Beetz,  
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