


Dr. Nico Blodow  
List of Publications

[C1] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,  
*Inferring Generalized Pick-and-Place Tasks from Pointing Gestures*,  

[C2] Nico Blodow, Lucian Cosmin Goron, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,  
*Autonomous Semantic Mapping for Robots Performing Everyday Manipulation Tasks in Kitchen Environments*,  

[C3] Zoltan-Csaba Marton, Nico Blodow and Michael Beetz,  
*Advantages of Spatial-temporal Object Maps for Service Robotics*,  
*IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO)*, Half-Moon Bay, CA, USA, October 2-4 2011.

[C4] Aitor Aldoma, Markus Vince, Nico Blodow, David Gossow, Suat Gedikli, Radu Bogdan Rusu and Gary R. Bradski,  
*CAD-model recognition and 6DOF pose estimation using 3D cues*,  
*IEEE International Conference on Computer Vision Workshops, ICCV 2011 Workshops, Barcelona, Spain, November 6-13, 2011*, 585-592, 2011.

[C1] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz,  
*Making Sense of 3D Data*,  

[C2] Zoltan-Csaba Marton, Dejan Pangercic, Nico Blodow, Jonathan Kleinehellefort and Michael Beetz,  
*General 3D Modelling of Novel Objects from a Single View*,  

[C3] Nico Blodow, Dominik Jain, Zoltan-Csaba Marton and Michael Beetz,  
*Perception and Probabilistic Anchoring for Dynamic World State Logging*,  

[C1] Radu Bogdan Rusu, Zoltan Csaba Marton, Nico Blodow, Andreas Holzbach and Michael Beetz,  
*Model-based and Learned Semantic Object Labeling in 3D Point Cloud Maps of Kitchen Environments*,  

[C2] Radu Bogdan Rusu, Nico Blodow, Zoltan Csaba Marton and Michael Beetz,  
*Close-range Scene Segmentation and Reconstruction of 3D Point Cloud Maps for Mobile Manipulation in Human Environments*,  


[C5] Radu Bogdan Rusu, Jan Bandouch, Zoltan Csaba Marton, Nico Blodow and Michael Beetz,
Action Recognition in Intelligent Environments using Point Cloud Features Extracted from Silhouette Sequences,
IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN), Muenchen, Germany, 2008.

[C6] Radu Bogdan Rusu, Zoltan Csaba Marton, Nico Blodow and Michael Beetz,
Persistent Point Feature Histograms for 3D Point Clouds,

[C7] Radu Bogdan Rusu, Zoltan Csaba Marton, Nico Blodow, Mihai Emanuel Dolha and Michael Beetz,
Functional Object Mapping of Kitchen Environments,

[C8] Radu Bogdan Rusu, Nico Blodow, Zoltan Csaba Marton and Michael Beetz,
Aligning Point Cloud Views using Persistent Feature Histograms,

[C1] Radu Bogdan Rusu, Nico Blodow, Zoltan-Csaba Marton, Alina Soos and Michael Beetz,
Towards 3D Object Maps for Autonomous Household Robots,