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List of Publications

[C1] Michael Beetz, Ferenc Balint-Benczedi, Nico Blodow, Daniel Nyga, Thiemo Wiedemeyer and Zoltan-Csaba Marton,
RoboSherlock: Unstructured Information Processing for Robot Perception,

[J1] Marton, Zoltan-Csaba, Balint-Benczedi, Ferenc, Mozos, Oscar Martinez, Blodow, Nico, Kanezaki, Asako, Goron, Lucian Cosmin, Pangercic, Dejan, Beetz and Michael,
Part-Based Geometric Categorization and Object Reconstruction in Cluttered Table-Top Scenes,

[C1] Karol Hausman, Ferenc Balint-Benczedi, Dejan Pangercic, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz,
Tracking-based Interactive Segmentation of Textureless Objects,

[C2] Kriegel, Simon, Brucker, Manuel, Marton, Zoltan-Csaba, Bodenmuller, Tim, Suppa and Michael,
Combining object modeling and recognition for active scene exploration,

[C3] Rink, Christian, Marton, Zoltan-Csaba, Seth, Daniel, Bodenmuller, Tim, Suppa and Michael,
Feature based particle filter registration of 3D surface models and its application in robotics,

[C4] Nissler, Christian, Marton, Zoltan-Csaba, Suppa and Michael,
Sample consensus fitting of bivariate polynomials for initializing EM-based modeling of smooth 3D surfaces,

Tutorial: Point Cloud Library: Three-Dimensional Object Recognition and 6 DOF Pose Estimation,

[J2] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz,
Ensembles of Strong Learners for Multi-cue Classification,
Pattern Recognition Letters (PRL), Special Issue on Scene Understandings and Behaviours Analysis, 2012.
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[C1] Karol Hausman, Christian Bersch, Dejan Pangercic, Sarah Osentoski, Zoltan-Csaba Marton and Michael Beetz,
Segmentation of Cluttered Scenes through Interactive Perception,

[C2] Ferenc Balint-Benczedi, Zoltan-Csaba Marton and Michael Beetz,
Efficient Part-Graph Hashes for Object Categorization,
5th International Conference on Cognitive Systems (CogSys), 2012.

[C3] Zoltan-Csaba Marton, Ferenc Balint-Benczedi, Florian Seidel, Lucian Cosmin Goron and Michael Beetz,
Object Categorization in Clutter using Additive Features and Hashing of Part-graph Descriptors,
Proceedings of Spatial Cognition (SC), Abbey Kloster Seeon, Germany, 2012.

[C4] Christian Bersch, Dejan Pangercic, Sarah Osentoski, Karol Hausman, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz,
Segmentation of Textured and Textureless Objects through Interactive Perception,

[C5] Lucian Cosmin Goron, Zoltan Csaba Marton, Gheorghe Lazea and Michael Beetz,
Segmenting Cylindrical and Box-like Objects in Cluttered 3D Scenes,
7th German Conference on Robotics (ROBOTIK), Munich, Germany, May 2012.

[C6] Zoltan-Csaba Marton, Florian Seidel and Michael Beetz,
Towards Modular Spatio-temporal Perception for Task-adapting Robots,
Postgraduate Conference on Robotics and Development of Cognition (RobotDoC-PhD),
a satellite event of the 22nd International Conference on Artificial Neural Networks (ICANN), Lausanne, Switzerland, 2012.

[C7] Vladyslav Usenko, Florian Seidel, Zoltan-Csaba Marton and Dejan Pangercic Michael Beetz,
Furniture Classification using WWW CAD Models,
IROS12 Workshop on Active Semantic Perception (ASP12), Vilamoura, Portugal, October 7 2012.

[J1] Oscar Martinez Mozos, Zoltan Csaba Marton and Michael Beetz,
Furniture Models Learned from the WWW – Using Web Catalogs to Locate and Categorize Unknown Furniture Pieces in 3D Laser Scans,

[J2] Zoltan Csaba Marton, Dejan Pangercic, Nico Blodow and Michael Beetz,
Combined 2D-3D Categorization and Classification for Multimodal Perception Systems,
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[C1] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,  
*Inferring Generalized Pick-and-Place Tasks from Pointing Gestures*,  

[C2] Nico Blodow, Lucian Cosmin Goron, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,  
*Autonomous Semantic Mapping for Robots Performing Everyday Manipulation Tasks in Kitchen Environments*,  

[C3] Zoltan-Csaba Marton, Nico Blodow and Michael Beetz,  
*Advantages of Spatial-temporal Object Maps for Service Robotics*,  
*IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO)*, Half-Moon Bay, CA, USA, October 2-4 2011.

[C4] Asako Kanezaki, Zoltan-Csaba Marton, Dejan Pangercic, Tatsuya Harada, Yasuo Kuniyoshi and Michael Beetz,  
*Voxelized Shape and Color Histograms for RGB-D*,  

[C5] Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz,  
*Efficient Surface and Feature Estimation in RGBD*,  

[C1] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz,  
*Making Sense of 3D Data*,  

[C2] Zoltan-Csaba Marton, Dejan Pangercic, Nico Blodow, Jonathan Kleinehellefort and Michael Beetz,  
*General 3D Modelling of Novel Objects from a Single View*,  

[C3] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz,  
*Hierarchical Object Geometric Categorization and Appearance Classification for Mobile Manipulation*,  

[C4] Nico Blodow, Dominik Jain, Zoltan-Csaba Marton and Michael Beetz,  
*Perception and Probabilistic Anchoring for Dynamic World State Logging*,  


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[C1] Radu Bogdan Rusu, Nico Blodow, Zoltan-Csaba Marton, Alina Soos and Michael Beetz, 
Towards 3D Object Maps for Autonomous Household Robots,