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[J1] Marton, Zoltan-Csaba, Balint-Benczedi, Ferenc, Mozos, Oscar Martinez, Blodow, Nico, Kanezaki, Asako, Goron, Lucian Cosmin, Pangercic, Dejan, Beetz and Michael, 
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Context Aware Shared Autonomy for Robotic Manipulation Tasks, 

[C2] Karol Hausman, Ferenc Balint-Benczedi, Dejan Pangercic, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz, 
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[J1] Michael Beetz, Dominik Jain, Lorenz Mösenlechner, Moritz Tenorth, Lars Kunze, Nico Blodow and Dejan Pangercic, 
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[C1] Karol Hausman, Christian Bersch, Dejan Pangercic, Sarah Osentoski, Zoltan-Csaba Marton and Michael Beetz, 
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[C2] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz, 
Elaborative Evaluation of RGB-D based Point Cloud Registration for Personal Robots, 

[C3] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments, 

[C4] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 
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[C5] Christian Bersch, Dejan Pangercic, Sarah Osentoski, Karol Hausman, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz, 
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[C6] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
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[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz, 
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[J2] Zoltan Csaba Marton, Dejan Pangercic, Nico Blodow and Michael Beetz, 
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[C1] Michael Beetz, Ulrich Klank, Alexis Maldonado, Dejan Pangercic and Thomas Rühr, 
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[C2] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
Inferring Generalized Pick-and-Place Tasks from Pointing Gestures, 
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[C4] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz,
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[C1] Thomas Rühr, Dejan Pangercic and Michael Beetz,
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