Dejan Pangercic

List of Publications


[C5] Christian Bersch, Dejan Pangercic, Sarah Osentoski, Karol Hausman, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz, 
Segmentation of Textured and Textureless Objects through Interactive Perception, 

[C6] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
Semantic Object Maps for Robotic Housework - Representation, Acquisition and Use, 

The SHERPA project: smart collaboration between humans and ground-aerial robots for improving rescuing activities in alpine environments, 
*IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, College Station, Texas, USA, Nov. 5-8 2012.

[C8] Vladyslav Usenko, Florian Seidel, Zoltan-Csaba Marton and Dejan Pangercic Michael Beetz, 
Furniture Classification using WWW CAD Models, 
*IROS12 Workshop on Active Semantic Perception (ASP12)*, Vilamoura, Portugal, October 7 2012.

[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz, 
Web-enabled Robots – Robots that Use the Web as an Information Resource, 

[J2] Zoltan Csaba Marton, Dejan Pangercic, Nico Blodow and Michael Beetz, 
Combined 2D-3D Categorization and Classification for Multimodal Perception Systems, 

[C1] Michael Beetz, Ulrich Klank, Alexis Maldonado, Dejan Pangercic and Thomas Rühr, 
Robotic Roommates Making Pancakes - Look Into Perception-Manipulation Loop, 

[C2] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
Inferring Generalized Pick-and-Place Tasks from Pointing Gestures, 
Dejan Pangercic

List of Publications

[C3] Nico Blodow, Lucian Cosmin Goron, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,
*Autonomous Semantic Mapping for Robots Performing Everyday Manipulation Tasks in Kitchen Environments*,

[C4] Shulei Zhu, Dejan Pangercic and Michael Beetz,
*Contracting Curve Density Algorithm for Applications in Personal Robotics*,

[C5] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth,
*Robotic Roommates Making Pancakes*,

[C6] Dejan Pangercic, Vladimir Haltakov and Michael Beetz,
*Fast and Robust Object Detection in Household Environments Using Vocabulary Trees with SIFT Descriptors*,

[C7] Asako Kanezaki, Zoltan-Csaba Marton, Dejan Pangercic, Tatsuya Harada, Yasuo Kuniyoshi and Michael Beetz,
*Voxelized Shape and Color Histograms for RGB-D*,

[C8] Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz,
*Efficient Surface and Feature Estimation in RGBD*,

[C1] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz,
*Making Sense of 3D Data*,

[C2] Zoltan-Csaba Marton, Dejan Pangercic, Nico Blodow, Jonathan Kleinehellefort and Michael Beetz,
*General 3D Modelling of Novel Objects from a Single View*,

[C3] Dejan Pangercic, Moritz Tenorth, Dominik Jain and Michael Beetz,
*Combining Perception and Knowledge Processing for Everyday Manipulation*,
Dejan Pangercic

List of Publications

[C4] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz,
Hierarchical Object Geometric Categorization and Appearance Classification for Mobile Manipulation,

[C1] Ulrich Klank, Dejan Pangercic, Radu Bogdan Rusu and Michael Beetz,
Real-time CAD Model Matching for Mobile Manipulation and Grasping,

[C2] Christoph Ertelt, Thomas Rühr, Dejan Pangercic, Kristina Shea and Michael Beetz,
Integration of Perception, Global Planning and Local Planning in the Manufacturing Domain,

[C3] Florian Friesdorf, Dejan Pangercic, Heiner Bubb and Michael Beetz,
Mutually Augmented Cognition,

[C4] Dejan Pangercic, Rok Tavcar, Moritz Tenorth and Michael Beetz,
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Proceedings of the International Conference on Advanced Robotics (ICAR)., Munich, Germany, June 22 - 26 2009.

[C5] Andreas Leha, Dejan Pangercic, Thomas Rühr and Michael Beetz,
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[C6] Michael Beetz, Nico Blodow, Ulrich Klank, Zoltan Csaba Marton, Dejan Pangercic and Radu Bogdan Rusu,
CoP-Man – Perception for Mobile Pick-and-Place in Human Living Environments,

[C1] Thomas Rühr, Dejan Pangercic and Michael Beetz,
Structured Reactive Controllers and Transformational Planning for Manufacturing,

[C2] Dejan Pangercic, Radu Bogdan Rusu and Michael Beetz,
3D-Based Monocular SLAM for Mobile Agents Navigating in Indoor Environments,
An Integrated Approach to Realize the Cognitive Machine Shop,