Dejan Pangercic

List of Publications

[J1] Marton, Zoltan-Csaba, Balint-Benczedi, Ferenc, Mozos, Oscar Martinez, Blodow, Nico, Kanezaki, Asako, Goron, Lucian Cosmin, Pangercic, Dejan, Beetz and Michael, 
Part-Based Geometric Categorization and Object Reconstruction in Cluttered Table-Top Scenes, 

[C1] Thomas Witzig, J. Marius Zöllner, Dejan Pangercic, Sarah Osentoski, Philip Roan, Rainer Jäkel and Rüdiger Dillmann, 
Context Aware Shared Autonomy for Robotic Manipulation Tasks, 

[C2] Karol Hausman, Ferenc Balint-Benczedi, Dejan Pangercic, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz, 
Tracking-based Interactive Segmentation of Textureless Objects, 

[J1] Michael Beetz, Dominik Jain, Lorenz Mösenlechner, Moritz Tenorth, Lars Kunze, Nico Blodow and Dejan Pangercic, 
Cognition-Enabled Autonomous Robot Control for the Realization of Home Chore Task Intelligence, 
Proceedings of the IEEE, Special Issue on Quality of Life Technology, 100(8): 2454-2471, 2012.

[C1] Karol Hausman, Christian Bersch, Dejan Pangercic, Sarah Osentoski, Zoltan-Csaba Marton and Michael Beetz, 
Segmentation of Cluttered Scenes through Interactive Perception, 

[C2] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz, 
Elaborative Evaluation of RGB-D based Point Cloud Registration for Personal Robots, 

[C3] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments, 

[C4] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 
[C5] Christian Bersch, Dejan Pangercic, Sarah Osentoski, Karol Hausman, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz, 
Segmentation of Textured and Textureless Objects through Interactive Perception, 

[C6] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
Semantic Object Maps for Robotic Housework - Representation, Acquisition and Use, 

The SHERPA project: smart collaboration between humans and ground-aerial robots for improving rescuing activities in alpine environments, 
*IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, College Station, Texas, USA, Nov. 5-8 2012.

[C8] Vladyslav Usenko, Florian Seidel, Zoltan-Csaba Marton and Dejan Pangercic Michael Beetz, 
Furniture Classification using WWW CAD Models, 
*IROS12 Workshop on Active Semantic Perception (ASP12)*, Vilamoura, Portugal, October 7 2012.

[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz, 
Web-enabled Robots – Robots that Use the Web as an Information Resource, 

[J2] Zoltan Csaba Marton, Dejan Pangercic, Nico Blodow and Michael Beetz, 
Combined 2D-3D Categorization and Classification for Multimodal Perception Systems, 

[C1] Michael Beetz, Ulrich Klank, Alexis Maldonado, Dejan Pangercic and Thomas Rühr, 
Robotic Roommates Making Pancakes - Look Into Perception-Manipulation Loop, 

[C2] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
Inferring Generalized Pick-and-Place Tasks from Pointing Gestures, 


[C4] Zoltan-Csaba Marton, Dejan Pangercic, Radu Bogdan Rusu, Andreas Holzbach and Michael Beetz,
Hierarchical Object Geometric Categorization and Appearance Classification for Mobile Manipulation,

[C1] Ulrich Klank, Dejan Pangercic, Radu Bogdan Rusu and Michael Beetz,
Real-time CAD Model Matching for Mobile Manipulation and Grasping,

[C2] Christoph Ertelt, Thomas Rühr, Dejan Pangercic, Kristina Shea and Michael Beetz,
Integration of Perception, Global Planning and Local Planning in the Manufacturing Domain,

[C3] Florian Friesdorf, Dejan Pangercic, Heiner Bubb and Michael Beetz,
Mutually Augmented Cognition,
Proceedings of the International Conference on Social Robotics (ICSR), 2009.

[C4] Dejan Pangercic, Rok Tavcar, Moritz Tenorth and Michael Beetz,
Visual Scene Detection and Interpretation using Encyclopedic Knowledge and Formal Description Logic,
Proceedings of the International Conference on Advanced Robotics (ICAR), Munich, Germany, June 22 - 26 2009.

[C5] Andreas Leha, Dejan Pangercic, Thomas Rühr and Michael Beetz,
Optimization of Simulated Production Process Performance using Machine Learning,

[C6] Michael Beetz, Nico Blodow, Ulrich Klank, Zoltan Csaba Marton, Dejan Pangercic and Radu Bogdan Rusu,
CoP-Man – Perception for Mobile Pick-and-Place in Human Living Environments,

[C1] Thomas Rühr, Dejan Pangercic and Michael Beetz,
Structured Reactive Controllers and Transformational Planning for Manufacturing,

[C2] Dejan Pangercic, Radu Bogdan Rusu and Michael Beetz,
3D-Based Monocular SLAM for Mobile Agents Navigating in Indoor Environments,

An Integrated Approach to Realize the Cognitive Machine Shop,