EnvMod: Automated environment modeling
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[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz,
*Ensembles of Strong Learners for Multi-cue Classification,* 
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[C2] Ross Kidson, Darko Stanimirovic, Dejan Pangercic and Michael Beetz,
*Elaborative Evaluation of RGB-D based Point Cloud Registration for Personal Robots,* 

[C3] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers,
*A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,* 

[C4] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
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[C5] Ferenc Balint-Benczedi, Zoltan-Csaba Marton and Michael Beetz,
*Efficient Part-Graph Hashes for Object Categorization,* 
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[C6] Zoltan-Csaba Marton, Ferenc Balint-Benczedi, Florian Seidel, Lucian Cosmin Goron and Michael Beetz,
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[C7] Christian Bersch, Dejan Pangercic, Sarah Osentoski, Karol Hausman, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz,
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[C8] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
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[C9] Lucian Cosmin Goron, Zoltan Csaba Marton, Gheorghe Lazea and Michael Beetz, *Segmenting Cylindrical and Box-like Objects in Cluttered 3D Scenes*, 7th German Conference on Robotics (ROBOTIK), Munich, Germany, May 2012.


EnvMod: Automated environment modeling

List of Publications

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[C7] Manabu Saito, Haseru Chen, Kei Okada, Masayuki Inaba, Lars Kunze and Michael Beetz, 
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[C8] Asako Kanezaki, Zoltan-Csaba Marton, Dejan Pangercic, Tatsuya Harada, Yasuo Kuniyoshi and Michael Beetz, 
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[C9] Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz, 
*Efficient Surface and Feature Estimation in RGBD*, 

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EnvMod: Automated environment modeling

List of Publications


EnvMod: Automated environment modeling

List of Publications

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EnvMod: Automated environment modeling List of Publications


EnvMod: Automated environment modeling List of Publications

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