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[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework, 

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermsdörfer, 
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[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
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[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz, 
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[C1] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz, 
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[C2] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments, 

[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments, 

[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba, 
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[C5] Moritz Tenorth and Michael Beetz,
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[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
Semantic Object Maps for Household Tasks,

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr,
CRAM – a Cognitive Robot Abstract Machine,

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi,
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[C9] Moritz Tenorth and Michael Beetz,
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[C10] Moritz Tenorth and Michael Beetz,
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[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
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[C12] L. Marconi, C. Melchiorri, M. Beetz, D. Pangercic†, R. Siegwart, S. Leutenegger, R. Car-
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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch,
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[C1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
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