KnowRob: Knowledge processing for robots List of Publications


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[C5] Moritz Tenorth and Michael Beetz, 
Knowledge Processing for Autonomous Robot Control,  

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks,  

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine,  

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi, 
RoboEarth Action Recipe Execution,  

[C9] Moritz Tenorth and Michael Beetz, 
Exchange of Action-related Information among Autonomous Robots,  

[C10] Moritz Tenorth and Michael Beetz, 
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects,  

[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
Semantic Object Maps for Robotic Housework - Representation, Acquisition and Use,  

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[C4] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
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