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[C1] Michael Beetz, Ferenc Balint-Benczedi, Nico Blodow, Daniel Nyga, Thiemo Wiedemeyer and Zoltan-Csaba Marton,
RoboSherlock: Unstructured Information Processing for Robot Perception, 

[J1] Marton, Zoltan-Csaba, Balint-Benczedi, Ferenc, Mozos, Oscar Martinez, Blodow, Nico, Kanezaki, Asako, Goron, Lucian Cosmin, Pangercic, Dejan, Beetz and Michael,
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[C1] Karol Hausman, Ferenc Balint-Benczedi, Dejan Pangercic, Zoltan-Csaba Marton, Ryohei Ueda, Kei Okada and Michael Beetz,
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[C2] Kriegel, Simon, Brucker, Manuel, Marton, Zoltan-Csaba, Bodenmuller, Tim, Suppa and Michael,
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[C3] Rink, Christian, Marton, Zoltan-Csaba, Seth, Daniel, Bodenmuller, Tim, Suppa and Michael,
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[C4] Nissler, Christian, Marton, Zoltan-Csaba, Suppa and Michael,
Sample consensus fitting of bivariate polynomials for initializing EM-based modeling of smooth 3D surfaces, 

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[C1] Karol Hausman, Christian Bersch, Dejan Pangercic, Sarah Osentoski, Zoltan-Csaba Marton and Michael Beetz,
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[C2] Ferenc Balint-Benczedi, Zoltan-Csaba Marton and Michael Beetz,
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*Inferring Generalized Pick-and-Place Tasks from Pointing Gestures,*

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[C5] Zoltan-Csaba Marton, Dejan Pangercic and Michael Beetz, 
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