Computer Vision Group Munich
List of Publications

RoboSherlock: Unstructured Information Processing Framework for Robotic Perception,
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[PhD1] Nico Blodow,
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[J2] Moritz Tenorth and Michael Beetz,
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Learning Probability Distributions over Partially-Ordered Human Everyday Activities,

[C6] Lorenz Mösenlechner and Michael Beetz,
Fast Temporal Projection Using Accurate Physics-Based Geometric Reasoning,

[C7] Kriegel, Simon, Brucker, Manuel, Marton, Zoltan-Csaba, Bodenmuller, Tim, Suppa and Michael,
Combining object modeling and recognition for active scene exploration,

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