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[J1] Michael Beetz, Tom Arbuckle, Thorsten Belker, Maren Bennewitz, Armin Cremers, Dirk Hähnel and Dirk Schulz,  
*Enabling Autonomous Robots to Perform Complex Tasks*,  
*KI - Künstliche Intelligenz; Special Issue on Autonomous Robots*, 2000.

[J2] Sebastian Thrun, Michael Beetz, Maren Bennewitz, Armin Cremers, Frank Dellaert, Dieter Fox, Dirk Hähnel, Charles Rosenberg, Nicholas Roy, Jamieson Schulte and Dirk Schulz,  
*Probabilistic Algorithms and the Interactive Museum Tour-Guide Robot Minerva*,  

[B1] Michael Beetz,  
*Concurrent Reactive Plans: Anticipating and Forestalling Execution Failures*,  

[C1] Robert Hanek and Thorsten Schmitt,  
*Vision-Based Localization and Data Fusion in a System of Cooperating Mobile Robots*,  

[C2] Robert Hanek, Thorsten Schmitt, Michael Klupsch and Sebastian Buck,  
*From Multiple Images to a Consistent View*,  

[C3] Sebastian Buck and Martin Riedmiller,  
*Learning Situation Dependent Success Rates Of Actions In A RoboCup Scenario*,  

[C4] Sebastian Buck, Robert Hanek, Michael Klupsch and Thorsten Schmitt,  
*Agilo RoboCuppers: RoboCup Team Description*,  

[C5] Rainer Malaka and Sebastian Buck,  
*Solving Nonlinear Optimization Problems Using Networks Of Spiking Neurons*,  

[C6] Michael Beetz and Thorsten Belker,  
*Environment and Task Adaptation for Robotic Agents*,  

[C7] Michael Beetz and Thorsten Belker,  
[C8] Michael Beetz, Jürgen Schumacher, Armin Cremers, Bernd Hellingrath and Christian Mazzocco,
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[C9] Michael Beetz and Henrik Grosskreutz,
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[C10] Michael Beetz,
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[PhD1] Christof Ridder,
Interpretation von Videobildfolgen zur Beobachtung artikularer Bewegung von Personen anhand eines generischen 3D Objektmodells,

[PhD2] Michael Klupsch,
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[PhD3] Michael Beetz,
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[C1] Thorsten Bandlow, Michael Klupsch, Robert Hanek and Thorsten Schmitt,
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[C2] Thorsten Bandlow, Michael Klupsch, Robert Hanek and Thorsten Schmitt,
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[C3] Tom Arbuckle and Michael Beetz,
Controlling Image Processing: Providing Extensible, Run-time Configurable Functionality on Autonomous Robots,

[C4] Michael Beetz and Thorsten Belker,
Experience- and Model-based Transformational Learning of Symbolic Behavior Specifications,
[C5] T. Arbuckle and M. Beetz,
Extensible, Runtime-configurable Image Processing on Robots — the RECIPE system,

[C6] Michael Beetz, Maren Bennewitz and Henrik Grosskreutz,
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[C7] Michael Beetz,
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[C8] Michael Beetz, Markus Giesenschlag, Roman Englert, Eberhard Gülch and Armin Cremers,
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[J1] Michael Beetz, Wolfram Burgard, Dieter Fox and Armin Cremers,
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[C2] Michael Klupsch,
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[PhD1] Stefan Lanser,
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