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*Perspectives on Plan-based Multiagent Systems for Distributed Supply Chain Management in the Steel Industry*,

[C9] Michael Beetz and Henrik Grosskreutz,
*Probabilistic Hybrid Action Models for Predicting Concurrent Percept-driven Robot Behavior*,

[C10] Michael Beetz,
*Runtime Plan Adaptation in Structured Reactive Controllers*,

[PhD1] Christof Ridder,
*Interpretation von Videobildfolgen zur Beobachtung artikularer Bewegung von Personen anhand eines generischen 3D Objektmodells*,

[PhD2] Michael Klupsch,
*Objektorientierte Daten- und Zeitmodelle für die Echtzeit-Bildfolgenauswertung*,

[PhD3] Michael Beetz,
*Plan-based Control of Robotic Agents*,
University of Bonn, 2000.

[C1] Thorsten Bandlow, Michael Klupsch, Robert Hanek and Thorsten Schmitt,
*Fast Image Segmentation, Object Recognition and Localization in a RoboCup Scenario*,

[C2] Thorsten Bandlow, Michael Klupsch, Robert Hanek and Thorsten Schmitt,
*Agilo RoboCuppers: RoboCup Team Description*,

[C3] Tom Arbuckle and Michael Beetz,
*Controlling Image Processing: Providing Extensible, Run-time Configurable Functionality on Autonomous Robots*,

[C4] Michael Beetz and Thorsten Belker,
*Experience- and Model-based Transformational Learning of Symbolic Behavior Specifications*,
[C5] T. Arbuckle and M. Beetz,  
Extensible, Runtime-configurable Image Processing on Robots — the RECIPE system,  

[C6] Michael Beetz, Maren Bennewitz and Henrik Grosskreutz,  
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[C7] Michael Beetz,  
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[C8] Michael Beetz, Markus Giesenschlag, Roman Englert, Eberhard Gülch and Armin Cremers,  
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[J1] Michael Beetz, Wolfram Burgard, Dieter Fox and Armin Cremers,  
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[C1] M. Beetz and H. Grosskreutz,  
Causal Models of Mobile Service Robot Behavior,  

[C2] Michael Klupsch,  
Object-Oriented Representation of Time-Varying Data Sequences in Multi-agent Systems,  

[C3] Michael Klupsch, Maximilian Lückenhaus, Christoph Zierl, Ivan Laptev, Thorsten Bandlow, Marc Grimme, Ignaz Kellerer and Fabian Schwarzer,  
Agilo RoboCuppers: RoboCup Team Description,  

[C4] Tom Arbuckle and Michael Beetz,  
RECIPE - A System for Building Extensible, Run-time Configurable, Image Processing Systems,  
[C5] Michael Beetz and Maren Bennewitz,  
Planning, Scheduling, and Plan Execution for Autonomous Robot Office Couriers,  

[C6] Michael Beetz, Tom Arbuckle, Armin Cremers and Markus Mann,  
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[C1] R. Bertelsmeier and Bernd Radig,  
**Kontextunterstützte Analyse von Szenen mit bewegten Objekten.,**  