Cogito: Plan-based Control of Robotic Agents

[C1] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz, 
Robots that Validate Learned Perceptual Models, 

[C2] Ingo Kresse and Michael Beetz, 
Movement-aware Action Control – Integrating Symbolic and Control-theoretic Action Execution, 

[C3] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C1] Lorenz Mösenlechner and Michael Beetz, 
Parameterizing Actions to have the Appropriate Effects, 

[C2] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth, 
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List of Publications

[J1] Alexandra Kirsch,
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[C1] Andreas Fedrizzi, Lorenz Moesenlechner, Freek Stulp and Michael Beetz,
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[C2] Lorenz Mösenlechner, Armin Müller and Michael Beetz,
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[C2] Alexandra Kirsch and Michael Beetz,
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