KnowRob: Knowledge processing for robots List of Publications

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz,
Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework,

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermstößer,
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[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz,
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[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz,
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[C1] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz,
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[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz,
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[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba,
Searching Objects in Large-scale Indoor Environments: A Decision-theoretic Approach,
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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch,
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[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth,
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