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[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
*Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework*,

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermsdörfer, 
*Action sequencing and error production in stroke patients with apraxia – Behavioral modeling using Bayesian Logic Networks*,

[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
*Learning Probability Distributions over Partially-Ordered Human Everyday Activities*,

[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz, 
*Ensembles of Strong Learners for Multi-cue Classification*,
*Pattern Recognition Letters (PRL), Special Issue on Scene Understandings and Behaviours Analysis*, 2012.

[C1] Martin Schuster, Dominik Jain, Moritz Tenorth and Michael Beetz, 
*Learning Organizational Principles in Human Environments*,

[C2] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
*A Generalized Framework for Opening Doors and Drawers in Kitchen Environments*,

[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
*The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments*,

[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba, 
*Searching Objects in Large-scale Indoor Environments: A Decision-theoretic Approach*,
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[C5] Moritz Tenorth and Michael Beetz,
Knowledge Processing for Autonomous Robot Control,
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[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
Semantic Object Maps for Household Tasks,

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr,
CRAM – a Cognitive Robot Abstract Machine,

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi,
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[C9] Moritz Tenorth and Michael Beetz,
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[C10] Moritz Tenorth and Michael Beetz,
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects,

[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
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[C13] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiro Miyashita and Norihiro Hagita,
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[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz,
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[J2] Markus Waibel, Michael Beetz, Raffaello D’Andrea, Rob Janssen, Moritz Tenorth, Javier Civera, Jos Elfring, Dorian Gálvez-López, Kai Häussermann, J.M.M. Montiel, Alexander Perzylo, Björn Schießle, Oliver Zweigle and René van de Molengraft, 
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[C3] Daniel Nyga, Moritz Tenorth and Michael Beetz, 
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[C4] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz, 
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[C6] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth, 
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[C7] Manabu Saito, Haseoru Chen, Kei Okada, Masayuki Inaba, Lars Kunze and Michael Beetz, 
**Semantic Object Search in Large-scale Indoor Environments,**

[PhD1] Moritz Tenorth, 
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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch,
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[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth,
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[J3] Moritz Tenorth, Dominik Jain and Michael Beetz,
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[C1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
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[C4] Michael Beetz, Lorenz Mösenlechner and Moritz Tenorth,
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[C1] Dejan Pangeric, Rok Tavcar, Moritz Tenorth and Michael Beetz,
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