Naive Physics reasoning by simulation

List of Publications

[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz,
Simulation-based Temporal Projection of Everyday Robot Object Manipula-
tion,
Yolum, Tumer, Stone and Sonenberg(Eds.), Proc. of the 10th Int. Conf. on Autonomous
Agents and Multiagent Systems (AAMAS 2011), Taipei, Taiwan, IFAAMAS, May, 2–6
2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
Logic Programming with Simulation-based Temporal Projection for Everyday
Robot Object Manipulation,
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), San

[C1] Lorenz Mösengechner and Michael Beetz,
Using Physics- and Sensor-based Simulation for High-fidelity Temporal Pro-
jection of Realistic Robot Behavior,
19th International Conference on Automated Planning and Scheduling (ICAPS’09), 2009.