RoboEarth: Knowledge-exchange between robists of Publications

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework, 

[C1] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
Learning Probability Distributions over Partially-Ordered Human Everyday Activities, 

[C1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments, 

[C2] Moritz Tenorth and Michael Beetz, 
Knowledge Processing for Autonomous Robot Control, 
AAAI Spring Symposium on Designing Intelligent Robots: Reintegrating AI, Stanford, CA, USA, March 26–28 2012.

[C3] Michael Beetz, Moritz Tenorth, Dejan Pangeric and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 

[C4] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C5] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi, 
RoboEarth Action Recipe Execution, 

[C6] Moritz Tenorth and Michael Beetz, 
Exchange of Action-related Information among Autonomous Robots, 

[C7] Moritz Tenorth and Michael Beetz, 
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects, 

[C8] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiro Miyashita and Norihiro Hagita, 
Towards a Networked Robot Architecture for Distributed Task Execution and Knowledge Exchange, 
Third International Workshop on Standards and Common Platforms for Robotics (SCPR 2012), in conjunction with SIMPAR 2012, Tsukuba, Japan, November 5 2012.
[J1] Markus Waibel, Michael Beetz, Raffaello D’Andrea, Rob Janssen, Moritz Tenorth, Javier Civera, Jos Elfring, Dorian Gálvez-López, Kai Häussermann, J.M.M. Montiel, Alexander Perzylo, Björn Schießle, Oliver Zweigle and René van de Molengraft, 
RoboEarth - A World Wide Web for Robots, 

[C1] Lars Kunze, Tobias Roehm and Michael Beetz, 
Towards Semantic Robot Description Languages, 

[PhD1] Moritz Tenorth, 
Knowledge Processing for Autonomous Robots, 
Technische Universität München, 2011.

[R1] Moritz Tenorth and Michael Beetz, 
Deliverable D5.2: The RoboEarth Language – Language Specification, 