RoboEarth: Knowledge-exchange between collaborative publications


RoboEarth: Knowledge-exchange between robots

[J1] Markus Waibel, Michael Beetz, Raffaello D’Andrea, Rob Janssen, Moritz Tenorth, Javier Civera, Jos Elfring, Dorian Gálvez-López, Kai Häussermann, J.M.M. Montiel, Alexander Perzylo, Björn Schießle, Oliver Zweigle and René van de Molengraft,
RoboEarth - A World Wide Web for Robots,

[C1] Lars Kunze, Tobias Roehm and Michael Beetz,
Towards Semantic Robot Description Languages,

[PhD1] Moritz Tenorth,
Knowledge Processing for Autonomous Robots,
Technische Universität München, 2011.

[R1] Moritz Tenorth and Michael Beetz,
Deliverable D5.2: The RoboEarth Language – Language Specification,